

# Generalized Least Squares

Up until now, we have assumed that

$$Euu' = \sigma^2 I.$$

Now we generalize to let

$$Euu' = \Omega$$

where  $\Omega$  is restricted to be a positive definite, symmetric matrix.

## 1 Common Examples

### 1.1 Autoregressive Models

#### 1.1.1 AR(1)

$$\begin{aligned}u_t &= \rho u_{t-1} + e_t; \\|\rho| &< 1; \\e_t &\sim iid(0, \sigma^2).\end{aligned}$$

$$\begin{aligned}Varu_t &= Eu_t^2 = E(\rho u_{t-1} + e_t)^2 \\&= E[\rho^2 u_{t-1}^2 + 2\rho u_{t-1} e_t + e_t^2] \\&= \rho^2 Eu_{t-1}^2 + 2\rho Eu_{t-1} e_t + Ee_t^2 \\&= \rho^2 Eu_{t-1}^2 + Ee_t^2 \\&= \rho^2 Eu_t^2 + \sigma^2 \quad (\text{stationarity})\end{aligned}$$

$$\Rightarrow Varu_t = \frac{\sigma^2}{1 - \rho^2}.$$

$$\begin{aligned}Cov(u_t, u_{t-1}) &= Eu_t u_{t-1} = E(\rho u_{t-1} + e_t) u_{t-1} \\&= \rho Eu_{t-1}^2 + Ee_t u_{t-1} = \rho Eu_t^2 \\&= \frac{\rho \sigma^2}{1 - \rho^2}.\end{aligned}$$

$$\begin{aligned}Cov(u_t, u_{t-2}) &= Eu_t u_{t-2} = E(\rho u_{t-1} + e_t) u_{t-2} \\&= \rho Eu_{t-1} u_{t-2} + Ee_t u_{t-2} = \rho Eu_t u_{t-1} \\&= \frac{\rho^2 \sigma^2}{1 - \rho^2}.\end{aligned}$$

$$\text{Cov}(u_t, u_{t-n}) = \frac{\rho^n \sigma^2}{1 - \rho^2}.$$

$\Rightarrow$

$$\Omega = \frac{\sigma^2}{1 - \rho^2} \begin{pmatrix} 1 & \rho & \dots & \rho^{T-1} \\ \rho & 1 & \dots & \rho^{T-2} \\ \vdots & \vdots & \ddots & \vdots \\ \rho^{T-1} & \rho^{T-2} & \dots & 1 \end{pmatrix}$$

### 1.1.2 AR(2)

$$\begin{aligned} u_t &= \rho_1 u_{t-1} + \rho_2 u_{t-2} + e_t; \\ e_t &\sim iid(0, \sigma_e^2). \end{aligned}$$

$$\begin{aligned} \text{Var}u_t &= \sigma_0 = Eu_t^2 = E[\rho_1 u_{t-1} + \rho_2 u_{t-2} + e_t]^2 & (1) \\ &= \rho_1^2 Eu_{t-1}^2 + \rho_2^2 Eu_{t-2}^2 + Ee_t^2 \\ &\quad + 2\rho_1\rho_2 Eu_{t-1}u_{t-2} + 2\rho_1 Eu_{t-1}e_t + 2\rho_2 Eu_{t-2}e_t \\ &= \rho_1^2 \sigma_0 + \rho_2^2 \sigma_0 + \sigma_e^2 + 2\rho_1\rho_2 \sigma_1 \end{aligned}$$

where

$$\sigma_n = \text{Cov}(u_t, u_{t-n}).$$

$$\begin{aligned} \sigma_1 &= Eu_t u_{t-1} = E[\rho_1 u_{t-1} + \rho_2 u_{t-2} + e_t] u_{t-1} & (2) \\ &= \rho_1 Eu_{t-1}^2 + \rho_2 Eu_{t-2} u_{t-1} + Ee_t u_{t-1} \\ &= \rho_1 \sigma_0 + \rho_2 \sigma_1. \end{aligned}$$

We can write equations (1) and (2) in matrix form as

$$\begin{bmatrix} 1 - \rho_1^2 - \rho_2^2 & -2\rho_1\rho_2 \\ -\rho_1 & 1 - \rho_2 \end{bmatrix} \begin{pmatrix} \sigma_0 \\ \sigma_1 \end{pmatrix} = \begin{pmatrix} \sigma_e^2 \\ 0 \end{pmatrix} \quad (3)$$

and solve for

$$\begin{pmatrix} \sigma_0 \\ \sigma_1 \end{pmatrix} = \begin{bmatrix} 1 - \rho_1^2 - \rho_2^2 & -2\rho_1\rho_2 \\ -\rho_1 & 1 - \rho_2 \end{bmatrix}^{-1} \begin{pmatrix} \sigma_e^2 \\ 0 \end{pmatrix}.$$

The condition for stationarity is that the eigenvalues of

$$\begin{bmatrix} 1 - \rho_1^2 - \rho_2^2 & -2\rho_1\rho_2 \\ -\rho_1 & 1 - \rho_2 \end{bmatrix}^{-1}$$

are greater than one. Equation (3) is called the Yule-Walker equations.

Students should work out the Yule-Walker equations for an AR(3).

## 1.2 Moving Average

### 1.2.1 MA(1)

$$\begin{aligned} u_t &= \rho_0 e_t + \rho_1 e_{t-1}; \\ e_t &\sim iid(0, \sigma_e^2). \end{aligned}$$

$$\begin{aligned} Eu_t^2 &= E[\rho_0 e_t + \rho_1 e_{t-1}]^2 \\ &= \rho_0^2 Ee_t^2 + \rho_1^2 Ee_{t-1}^2 + 2\rho_0\rho_1 Ee_t e_{t-1} \\ &= \rho_0^2 \sigma_e^2 + \rho_1^2 \sigma_e^2; \end{aligned}$$

$$Eu_t u_{t-1} = E[\rho_0 e_t + \rho_1 e_{t-1}][\rho_0 e_{t-1} + \rho_1 e_{t-2}] = \rho_0 \rho_1 \sigma_e^2.$$

$$Eu_t u_{t-n} = E[\rho_0 e_t + \rho_1 e_{t-1}][\rho_0 e_{t-n} + \rho_1 e_{t-n-1}] = 0$$

if  $n > 1$ . Thus

$$\Omega = \sigma_e^2 \begin{bmatrix} \rho_0^2 + \rho_1^2 & \rho_0 \rho_1 & 0 & \cdots & 0 \\ \rho_0 \rho_1 & \rho_0^2 + \rho_1^2 & \rho_0 \rho_1 & \cdots & 0 \\ 0 & \rho_0 \rho_1 & \rho_0^2 + \rho_1^2 & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & \rho_0^2 + \rho_1^2 \end{bmatrix}$$

### 1.2.2 MA(n)

$$\begin{aligned} u_t &= \sum_{i=0}^n \rho_i e_{t-i} \\ e_t &\sim iid(0, \sigma_e^2). \end{aligned}$$

$$\begin{aligned} Eu_t^2 &= E\left[\sum_{i=0}^n \rho_i e_{t-i}\right]^2 = \sigma_e^2 \sum_{i=0}^n \rho_i^2; \\ Eu_t u_{t-1} &= E\left[\sum_{i=0}^n \rho_i e_{t-i}\right] \left[\sum_{i=0}^n \rho_i e_{t-i-1}\right] \\ &= E\left[\sum_{i=0}^n \rho_i e_{t-i}\right] \left[\sum_{i=1}^{n+1} \rho_{i-1} e_{t-i}\right] = \sigma_e^2 \sum_{i=1}^n \rho_i \rho_{i-1}; \\ Eu_t u_{t-k} &= \begin{cases} \sigma_e^2 \sum_{i=k}^n \rho_i \rho_{i-1} & \text{if } k \leq n \\ 0 & \text{if } k > n \end{cases}. \end{aligned}$$

### 1.3 ARMA

$$u_t = \sum_{i=1}^m \alpha_i u_{t-i} + \sum_{i=0}^n \rho_i e_{t-i}$$
$$e_t \sim iid(0, \sigma_e^2)$$

is an ARMA(m,n) process. Work out the Yule-Walker equations.

### 1.4 Heteroskedasticity

$$\Omega = \begin{pmatrix} \sigma_1^2 & 0 & \cdots & 0 \\ 0 & \sigma_2^2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \sigma_T^2 \end{pmatrix}.$$

### 1.5 Random Coefficients

Consider the model

$$y_t = X_t \beta_t + u_t$$

with

$$\beta_t \sim iid(\bar{\beta}, \Omega_\beta).$$

Then we can write the model as

$$y_t = X_t \bar{\beta} + X_t (\beta_t - \bar{\beta}) + u_t$$
$$= X_t \bar{\beta} + e_t$$

where

$$e_t = X_t (\beta_t - \bar{\beta}) + u_t.$$

$$Eee' = E[X(\beta - \bar{\beta}) + u][X(\beta - \bar{\beta}) + u]'$$
$$= X\Omega_\beta X' + \sigma_u^2 I.$$

### 1.6 Random Effects

Consider the model

$$y_{it} = X_{it}\beta + u_i + e_{it}, \quad i = 1, \dots, n; \quad t = 1, \dots, T$$
$$u_i \sim iid(0, \sigma_u^2); \quad e_{it} \sim iid(0, \sigma_e^2)$$

(explain panel data; give examples). Define

$$y_i = \begin{pmatrix} y_{i1} \\ y_{i2} \\ \vdots \\ y_{iT} \end{pmatrix}; \quad X_i = \begin{pmatrix} X_{i1} \\ X_{i2} \\ \vdots \\ X_{iT} \end{pmatrix}; \quad e_i = \begin{pmatrix} e_{i1} \\ e_{i2} \\ \vdots \\ e_{iT} \end{pmatrix}; \quad \iota = \begin{pmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{pmatrix}.$$

Then the model can be written as

$$y_i = X_i\beta + \iota u_i + e_i.$$

Now define

$$y = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix}; \quad X = \begin{pmatrix} X_1 \\ X_2 \\ \vdots \\ X_n \end{pmatrix}; \quad e = \begin{pmatrix} e_1 \\ e_2 \\ \vdots \\ e_n \end{pmatrix}; \quad u = \begin{pmatrix} \iota u_1 \\ \iota u_2 \\ \vdots \\ \iota u_n \end{pmatrix}.$$

Then the model can be written as

$$y = X\beta + v$$

with

$$v = u + e.$$

$$\begin{aligned} \Omega_v &= E v v' = E(u + e)(u + e)' \\ &= \begin{pmatrix} A & 0_T & \cdots & 0_T \\ 0_T & A & \cdots & 0_T \\ \vdots & \vdots & \ddots & \vdots \\ 0_T & 0_T & \cdots & A \end{pmatrix} \end{aligned}$$

where

$$A_{T \times T} = \begin{pmatrix} \sigma_u^2 + \sigma_e^2 & \sigma_u^2 & \cdots & \sigma_u^2 \\ \sigma_u^2 & \sigma_u^2 + \sigma_e^2 & \cdots & \sigma_u^2 \\ \vdots & \vdots & \ddots & \vdots \\ \sigma_u^2 & \sigma_u^2 & \cdots & \sigma_u^2 + \sigma_e^2 \end{pmatrix}.$$

## 2 GLS and OLS

Consider the model

$$y = X\beta + u, \quad u \sim (0, \Omega).$$

$$\widehat{\beta}_{OLS} = (X'X)^{-1} X'y = \beta + (X'X)^{-1} X'u$$

$$E\widehat{\beta}_{OLS} = \beta + E(X'X)^{-1} X'u = \beta + (X'X)^{-1} X'Eu = \beta.$$

$$\begin{aligned} D(\widehat{\beta}_{OLS}) &= E(X'X)^{-1} X'uu'X (X'X)^{-1} \\ &= (X'X)^{-1} X'Eu u'X (X'X)^{-1} \\ &= (X'X)^{-1} X'\Omega X (X'X)^{-1} \neq \sigma_u^2 (X'X)^{-1} \end{aligned}$$

(especially because there is no such object as  $\sigma_u^2$ ). Therefore,  $\widehat{\beta}_{OLS}$  is unbiased but the standard errors are wrong. We could correct the standard errors.

Alternatively, let

$$R'R = \Omega^{-1},$$

and consider

$$Ry = RX\beta + Ru.$$

Note that

$$\begin{aligned} ERu &= REu = 0; \\ ERuu'R' &= REuu'R' = R\Omega R' = I. \end{aligned}$$

Define

$$\begin{aligned} \widehat{\beta}_{GLS} &= [(RX)'(RX)]^{-1} [(RX)'(Ry)] \\ &= [X'R'RX]^{-1} [X'R'Ry] \\ &= [X'\Omega^{-1}X]^{-1} [X'\Omega^{-1}y]. \end{aligned}$$

Note that

$$\begin{aligned} \widehat{\beta}_{GLS} &= [X'\Omega^{-1}X]^{-1} [X'\Omega^{-1}y] \\ &= [X'\Omega^{-1}X]^{-1} [X'\Omega^{-1}(X\beta + u)] \\ &= [X'\Omega^{-1}X]^{-1} [X'\Omega^{-1}X\beta] + [X'\Omega^{-1}X]^{-1} [X'\Omega^{-1}u] \\ &= \beta + [X'\Omega^{-1}X]^{-1} [X'\Omega^{-1}u] \end{aligned}$$

$\Rightarrow$

$$\begin{aligned} E\widehat{\beta}_{GLS} &= \beta + E[X'\Omega^{-1}X]^{-1} [X'\Omega^{-1}u] \\ &= \beta + E[X'\Omega^{-1}X]^{-1} [X'\Omega^{-1}Eu] \\ &= \beta; \end{aligned}$$

$$\begin{aligned}
D(\hat{\beta}_{GLS}) &= E [X'\Omega^{-1}X]^{-1} [X'\Omega^{-1}u] [u'\Omega^{-1}X] [X'\Omega^{-1}X]^{-1} \\
&= [X'\Omega^{-1}X]^{-1} [X'\Omega^{-1}Euu'\Omega^{-1}X] [X'\Omega^{-1}X]^{-1} \\
&= [X'\Omega^{-1}X]^{-1} [X'\Omega^{-1}\Omega\Omega^{-1}X] [X'\Omega^{-1}X]^{-1} \\
&= [X'\Omega^{-1}X]^{-1} [X'\Omega^{-1}X] [X'\Omega^{-1}X]^{-1} \\
&= [X'\Omega^{-1}X]^{-1}.
\end{aligned}$$

Note that, if

$$\Omega = \sigma^2 I,$$

then

$$\begin{aligned}
\hat{\beta}_{GLS} &= [X'\Omega^{-1}X]^{-1} [X'\Omega^{-1}y] \\
&= [X'\sigma^{-2}IX]^{-1} [X'\sigma^{-2}Iy] \\
&= [X'X]^{-1} [X'y] = \hat{\beta}_{OLS},
\end{aligned}$$

and

$$D(\hat{\beta}_{GLS}) = [X'\sigma^{-2}IX]^{-1} = \sigma^2 [X'X]^{-1} = D(\hat{\beta}_{OLS}).$$

### 3 Realities of Data

#### 3.1 Testing for Heteroskedasticity and Other Deviations from $\Omega = \sigma^2 I$

##### 3.1.1 Durbin-Watson test statistic

$$\begin{aligned}
DW &= \frac{\sum_{t=2}^T (\hat{u}_t - \hat{u}_{t-1})^2}{\sum_{t=2}^T \hat{u}_{t-1}^2} \\
&= \frac{\sum_{t=2}^T (\hat{u}_t^2 - 2\hat{u}_t\hat{u}_{t-1} + \hat{u}_{t-1}^2)}{\sum_{t=2}^T \hat{u}_{t-1}^2}.
\end{aligned}$$

Consider the error structure associated with an AR(1) process.

$$\begin{aligned}
plim DW &= \frac{plim \frac{1}{T-1} \sum_{t=2}^T (\hat{u}_t^2 - 2\hat{u}_t\hat{u}_{t-1} + \hat{u}_{t-1}^2)}{plim \frac{1}{T-1} \sum_{t=2}^T \hat{u}_{t-1}^2} \\
&= \frac{2\sigma_0 - 2\sigma_1}{\sigma_0} = 2(1 - \rho).
\end{aligned}$$

$$\begin{aligned}
\text{If } \rho = 0, & \quad plim DW = 2 \\
\text{If } \rho \approx 1, & \quad plim DW \approx 0 \\
\text{If } \rho \approx -1, & \quad plim DW \approx 4
\end{aligned}$$

The distribution of the DW test can be found in tables. The DW test is a special case of a Lagrange-Multiplier test statistic (to be learned later).

### 3.1.2 White Heteroskedasticity Test Statistic

Consider

$$\Omega = \begin{pmatrix} \sigma_1^2 & 0 & \cdots & 0 \\ 0 & \sigma_2^2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \sigma_T^2 \end{pmatrix}$$

and

$$H_0 : \sigma_1^2 = \sigma_2^2 = \dots = \sigma_T^2 \quad \text{vs} \quad H_0 : \sigma_1^2 \neq \sigma_2^2 \neq \dots \neq \sigma_T^2.$$

Let  $\hat{u}$  be the OLS residuals. Consider regressing

$$\hat{u}_t^2 = \alpha_0 + \sum_{j \neq k} X_{tj} X_{tk} \alpha_{jk} + e_t.$$

Under  $H_0$ ,  $\alpha_{jk} = 0 \forall j, k$ . One can show that

$$TR^2 \sim \chi_{k(k+1)/2}^2.$$

### 3.2 Estimation when $\Omega$ is not Known

Consider the model

$$\begin{aligned} y &= X\beta + u \\ u &\sim (0, \Omega) \end{aligned}$$

and  $\Omega$  is unknown. Let  $\hat{u}$  be the OLS residuals. The goal is to use the residuals to construct a consistent estimate of  $\Omega$ . In general,  $\Omega$  has  $T(T+1)/2$  free parameters, and there are only  $T$  residuals (with only  $T - (n+1)$  degrees of freedom). So, to make any progress, we will have to put a lot of structure on  $\Omega$  (White heteroskedasticity corrected estimators are exceptions).

Examples:

1. AR(1): For an AR(1) model, there are only 2 parameters:  $\rho$  and  $\sigma_e^2$ . Consider

$$\hat{\rho} = \frac{\sum_{t=2}^T \hat{u}_t \hat{u}_{t-1}}{\sum_{t=2}^T \hat{u}_{t-1}^2}.$$

$$plim \hat{\rho} = \frac{plim \frac{1}{T-1} \sum_{t=2}^T \hat{u}_t \hat{u}_{t-1}}{plim \frac{1}{T-1} \sum_{t=2}^T \hat{u}_{t-1}^2} = \frac{\rho \sigma_e^2 / (1 - \rho^2)}{\sigma_e^2 / (1 - \rho^2)} = \rho.$$

Consider

$$\hat{\sigma}_e^2 = (1 - \hat{\rho}^2) \frac{1}{T-1} \sum_{t=2}^T \hat{u}_{t-1}^2.$$



$$plim \hat{\sigma}_e^2 = plim \left(1 - \hat{\rho}^2\right) \frac{\sigma_e^2}{(1 - \rho^2)} = (1 - \rho^2) \frac{\sigma_e^2}{(1 - \rho^2)} = \sigma_e^2.$$

We can plug  $\hat{\rho}$  and  $\hat{\sigma}_e^2$  into

$$\Omega = \frac{\sigma_e^2}{1 - \rho^2} \begin{pmatrix} 1 & \rho & \cdots & \rho^{T-1} \\ \rho & 1 & \cdots & \rho^{T-2} \\ \vdots & \vdots & \ddots & \vdots \\ \rho^{T-1} & \rho^{T-2} & \cdots & 1 \end{pmatrix}$$

to get a consistent estimate of  $\Omega$ , let's say  $\hat{\Omega}$ . Now plug  $\hat{\Omega}$  into the GLS estimator for  $\Omega$  to get

$$\hat{\beta}_{GLS} = \left[ X' \hat{\Omega}^{-1} X \right]^{-1} \left[ X' \hat{\Omega}^{-1} y \right].$$

We can no longer talk about  $E\hat{\beta}_{GLS}$ . But

$$\begin{aligned} \hat{\beta}_{GLS} &= \left[ X' \hat{\Omega}^{-1} X \right]^{-1} \left[ X' \hat{\Omega}^{-1} (X\beta + u) \right] \\ &= \left[ X' \hat{\Omega}^{-1} X \right]^{-1} \left[ X' \hat{\Omega}^{-1} X \beta \right] + \left[ X' \hat{\Omega}^{-1} X \right]^{-1} \left[ X' \hat{\Omega}^{-1} u \right] \\ &= \beta + \left[ X' \hat{\Omega}^{-1} X \right]^{-1} \left[ X' \hat{\Omega}^{-1} u \right]; \end{aligned}$$

$$\begin{aligned} plim \hat{\beta}_{GLS} &= \beta + plim \left[ \frac{X' \hat{\Omega}^{-1} X}{T} \right]^{-1} \left[ \frac{X' \hat{\Omega}^{-1} u}{T} \right] \\ &= \beta + \left[ plim \frac{X' \hat{\Omega}^{-1} X}{T} \right]^{-1} \left[ plim \frac{X' \hat{\Omega}^{-1} u}{T} \right] = \beta; \end{aligned}$$

and

$$\sqrt{T} \left( \hat{\beta}_{GLS} - \beta \right) \sim N(0, V)$$

with

$$V = \left[ plim \frac{X' \hat{\Omega}^{-1} X}{T} \right]^{-1} = \left[ plim \frac{X' \Omega^{-1} X}{T} \right]^{-1}.$$

2. MA(1): For an MA(1) model, there are three parameters:  $\rho_0$ ,  $\rho_1$ , and  $\sigma_e^2$ . Without loss of generality, we can set  $\rho_0 = 1$  (later we will understand this as an identification issue). What are good consistent estimates for  $\rho_1$  and  $\sigma_e^2$ ?

3. Random Effects: For a random effects model, there are two parameters:  $\sigma_u^2$  and  $\sigma_e^2$ . Let  $\widehat{v}_{it}$  be OLS residuals. Consider

$$s_1^2 = \frac{1}{nT} \sum_{i,t} \widehat{v}_{it}^2.$$

Since

$$Ev_{it}^2 = \sigma_u^2 + \sigma_e^2,$$

$$plim s_1^2 = \sigma_u^2 + \sigma_e^2. \quad (4)$$

Consider

$$s_2^2 = \frac{1}{n} \sum_i \widehat{v}_i^2$$

where

$$\widehat{v}_i = \frac{1}{T} \sum_t \widehat{v}_{it}.$$

Since

$$Ev_i^2 = \sigma_u^2 + \frac{1}{T} \sigma_e^2,$$

$$plim s_2^2 = \sigma_u^2 + \frac{1}{T} \sigma_e^2. \quad (5)$$

We can solve equations (4) and (5) together to get consistent estimates of  $\sigma_u^2$  and  $\sigma_e^2$ .

4. General  $\Omega$ : Assume we can parameterize  $\Omega$  in terms of a small number of parameters  $\alpha$ , and let  $\Omega(\alpha)$  represent  $\Omega$  as a function of  $\alpha$ . Let

$$\widehat{u} = (I - P_X) y$$

be OLS residuals. Define

$$\widehat{\alpha} = \arg \min_{\alpha} \left[ D^* (\Omega(\alpha)) - D^* \left( \frac{1}{T} \widehat{u} \widehat{u}' \right) \right]$$

where  $D^*(\cdot)$  takes the independent elements of the argument. Later we will show that  $\widehat{\alpha}$  is a consistent estimate of  $\alpha$ . Plug  $\widehat{\alpha}$  into  $\Omega(\alpha)$  to get  $\widehat{\Omega}$ , a consistent estimate of  $\Omega$ . Plug  $\widehat{\Omega}$  into the GLS estimator.

### 3.3 White Heteroskedasticity Correction

Consider the model

$$\begin{aligned}y_t &= X_t\beta + u_t \\u_t &\sim \text{ind}(0, \sigma_t^2).\end{aligned}$$

We know that

$$D(\widehat{\beta}_{OLS}) = (X'X)^{-1} X'\Omega X (X'X)^{-1}$$

where  $\Omega_{tt} = \sigma_t^2$  and  $\Omega_{ts} = 0$  for  $t \neq s$ . Consider  $X'\widehat{\Omega}X$  where  $\widehat{\Omega}_{tt} = \widehat{u}_t^2$  and  $\widehat{\Omega}_{ts} = 0$  for  $t \neq s$ .

$$\Rightarrow \text{plim} \frac{X'\widehat{\Omega}X}{T} = \frac{X'\Omega X}{T}$$

even though  $\text{plim}\widehat{\Omega}$  doesn't exist.

$$\Rightarrow \text{plim} \left( \frac{X'X}{T} \right)^{-1} \frac{X'\widehat{\Omega}X}{T} \left( \frac{X'X}{T} \right)^{-1} = \left( \frac{X'X}{T} \right)^{-1} \frac{X'\Omega X}{T} \left( \frac{X'X}{T} \right)^{-1}.$$

Newey-West generalizes this by letting

$$\widehat{\Omega}_{ts} = \frac{1}{T - |j - k|} \sum_t \widehat{u}_t \widehat{u}_s.$$